IAF-96-B.3.P103 NASA SCATTEROMETER EXPERIMENT

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Abstract

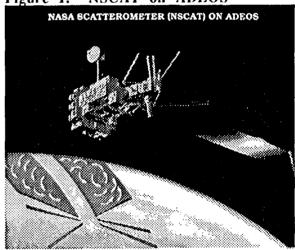
Satellite scatterometers are microwave radars capable of measuring surface vector winds (both speed a n d direction) over the oceans under al 1 weather conditions. The data gener ated from these instruments are used in scientific studies of upper ocean circulation, tropospheric dynamics, ai rsca interaction, and climate change; i n operational meteorology as a means to increase numerical weather forecast skill and the accuracy of storm warning predictions; and in commercial applications such as ship routing. scatterometer wind measurement tech nique was demonstrated with the flight of the Scasat Scatterometer in 1978. 'I'his summarizes the scatpaper terometry measurement technique, de scribes the design of the NASA Scatterometer (NSCAT) instrument recently aboard the National Space launched Development Agency of Japan's (NASDA) Advanced Earth Observing Satellite (ADEOS), presents first results from the NSCAT instrument, and dcscribes the future US program measuring surface marine wind vectors.

L Introduction

Contributing to both research. operacommercial Uses, scattional. and terometers are a unique spaceborne The instrument measures instrument. marine surface winds, which critical measurement for use in scientific studies of upper ocean circulation, tropospheric dynamics, air-sea interact ion, and climate change; in operational meteorology as a means to in numerical weather forecast crease skill and the accuracy of storm warning predictions; and in commercial an-

Copyright © 1996 by the International Astronautical Pederation. All rights reserved. Project Manager, NSCAT/SeaWinds Projects placations to enhance the safety and efficiency of ocean ship routing, sca floor drilling, and commercial fishing. With the launch of the NASA Scatterometer (NSCAT) in August 1996, the c first Ku-band scatterometer in 18 years is now returning data from space. An artist's rendering of the NSCAT in strument on the Advanced Earth Observing Satellite (ADEOS) is shown in Figure 1.

Figure 1. NSCAT on ADEOS



The first major collaboration in Earth remote sensing between NASA and the National Space Development Agency of Japan (NASDA), the three year NSCAT mission consists of a NASA-provided and a NASDA-provided instrument and launch vehicle. The spacecraft collaboration will continue flight of the next Ku-band scatterometer, ScaWinds, on NASDA's ADUOS II spacecraft in 1999. The ScaWinds in strument and the ADEOS II spacecraft will have a lifetime of three years, with a goal of five years of operation on orbit, and the launch is phased to

produce a continuous, six year (or 1 on - ger) time series of scatterometer data. If sufficient attitude control gas exists, the NSCAT/ADEOS combination will r c-main operational after the launch of ScaWinds/ADEOS 11 and the overlap b c-tween the two experiments will facilitate comprehensive calibration and validation between the two instruments and will increase coverage of the oceans.

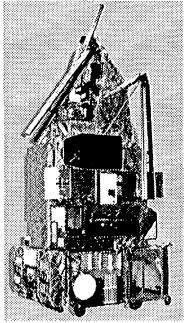
II. Marine W'd Measurement Requirements

The NSCAT measurement requirements for research purposes were established by NASA's interdisciplinary Surface Stress Working Group [1, 2]. They are defined in Table 1 and include the ability to measure winds between 3 and 30 m/s with an accuracy better than 2 m/s or 10% in speed (which ever is larger) and 20° in direction over a spatial wind ccl] vector resolution of 50 km; 90% or more of the oceans must b c observed at least once every two days; products for non-real time research applications must be produced within 2 weeks after data is acquired at thc processing center; and the instrument must be designed to acquire data for at least 3 years in order to allow investigation of annual and interannual variability.

Table 1	Major NSCAT Mission Requirements		
	Value	Accuracy/ Comment	
Wind	3-30 m/s	2 m/s or 10%,	
Speed	<u> </u>	whichever is larger	
Wind	3 -30 m/s	20° (rms - closest	
Direction		ambiguity) 4	
Spatial	50 ^km	Wind cells	
re solution	•	-	
Location 25km/1 Okrn		Absolute/	
Accuracy	(rms)	Relative	
Coverage 90% of		N/A	
-)cc-free oceans		
3 00	every 2 days	.	
Data	2 weeks of	At processing	
Prod.	receipt	kenter	
Mission	36 months	Includes checkout	
duration	•	ii	

III. NSCAT Mission Description The ADEOS spacecraft is a three axis stabilized spacecraft weighing 3.5 mctric tons, producing 4.5 kW of electrical energy at the end of life, having a n engineering body dimension of 4m x 4m x 7m, and supporting a suite of eight international instruments dedicated to Earth remote sensing. spacecraft was launched into a 797 k m sun synchronous orbit by the 11-1 I launch vehicle on August 17, 1996, and it continues to operate nominally. of the ADEOS science instruments from the USA and onc is from Fran cc; the other instruments are provided by NASDA and other Japanese agencies. In addition to NSCAT, the payload in eludes a wide-swath Ocean Color and Temperature Scanner (0(3"S), an Advanced Visible and Near-Infrared Radiometer (AVNIR), a Retroreflector I n Space (RIS), an Interferometer Monitor for Greenhouse Gases (1 MG), a Poand Directionality larization of the Earth's Reflectance (POLDER), a Total Ozone Mapping Spectrometer (1'OMS), and an Improved limb Atmospheric Spectrometer (ILAS). The NSCAT in strument onboard the ADEOS spacecraft is shown in Figure 2.

Figure 2. NSCAT on ADEOS



The NSCAT instrument has a mass of 279kg, including its six antennas, four antenna deployment mechanisms, three electronic units, and assorted RF waveguides, attachment fittings, and The instrument is electrical harness. on a 3.1m high structure. mounted dubbed the antenna tower, which was designed and fabricated by NASDA c n specifically to accommodate the NSCAT instrument. The towerdesign enables each of the NSCAT a n t c n nas to have a clear field-of-view (FOV) and allows the electronic boxes to rad iate their waste heat to deep space. The instrument uses 241W of orbital average power and acquires data continuously over the orbit, whether over ocean, icc or land. The science data is combined into digital bins onboard t h c instrument, effectively reducing data rate by 1000 to 2.9kb/s. The kc y NSCAT instrument resource parameters arc summarized and compared in '1'able 2 to the follow-on instrument, Winds, which is described later in the paper.

Table 2.

Instrument Accommodations Comparison

moti amont 110	commodations	Comparison
Resource	NSCAT	Sea Winds
Mass (kg)	. 279	: 198
Average Power		192
(W)		
Operations	Continuous	: Continuous
Data rate (kb/s):		16
On board	4 ant,	1 v-band
actuation	deployments	release
Swath scan	Static using	Mechanical
	Doppler	rotation
Antenna FOV	6 ant. each	1 ant. with 51°
(includes	with 50°	to nadir
keep out zones)	rel. to ant.	conical scan
	boresight	Алинини

IV. Theory of Operation

The NSCAT instrument is an active m i - crowave radar that measures the n o r - malized radar backscatter coefficient, σ_o , of the ocean surface from several different viewing geometries. Since wind stress over the ocean generates capillary waves which roughen the sca surface, changes in wind velocity

cause changes in surface roughness. The roughness changes modify the r a dar cross-section of the ocean and, hence, the magnitude of backs cattered The normalized radar crosssection itself is calculated using the basic radar equation which requires accurate measurements of the antenna gain, slant range, transmitted power. system losses, wavelength, effective illuminated area, and received back scattered power. From each i l lum inated location on the earth, the total r c ceived power is the sum of the back scattered power and a contribution r c suiting from instrument noise and the natural emissivity (at that frequency) from the earth-atmosphere system. 1 n order to determine the backscatter cross-section accurately, the noise power must be estimated and subtracted from the total received power.

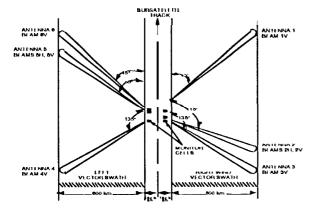
in general, σ_0 varies as a function of the surface wind speed, the inc idence angle of the illuminating radar beam, and the azimuth angle between the illamination direction and the wind di-A quantitative model of the backscatter as a function of the wind vector and the measurement geometry has been experimentally and analytically established by investigators over the past two decades [3, 4]. The back scatter mode] generally resembles a second-order sinusoidal function of wind direction, with the overall $\sigma_0 \mathbf{l}$ cv cl increasing with the wind speed.

A single scalar measurement is insu fficient to solve for both wind speed a n d wind direction. Multiple measurements obtained from different v i c wi ng geometries are required. With on 1 y two measurements taken 90° apart, t h c Scasat scatterometer generally had a four-fold ambiguity in wind direction, However, additional σ_0 values obtained from antennas at yet other angles using different polarizations provide additional information, allowing the wind direction to be uniquely defined. In the case of NSCAT, back scatter measurements are made with an

additional viewing angle having two polarizations, which substantially resolves the ambiguity.

The NSCAT design uses 4 antennas p c r side of the subsatellite track at three azimuth angles to obtain the necessary azimuthal looks (one of the stick a n tennas on each side is dual polarized). The antenna pattern is illustrated i n Figure 3. Each antenna produces a n footprint which is six instantaneous hundred kilometers long, but only six kilometers wide. These antenna patterns arc further resolved into back scatter measurements of 25km observation cells by means of summing pulse returns and Doppler filtering.

Figure 3. NSCAT Antenna Pattern



The technique makes use of the fact that the radar echo reflected from the ocean surface is Doppler shifted duc t o motion of the spacecraft relative to t h c The return echoes surface. carth's from different portions of the ant cnn a footprint have different Doppler shifts, with a larger shift at far swath and a smaller shift at near swath. By processing the returned signal with a n u m ber of bandpass filters of unequal NSCAT can resolve the bandwidth. 600km wide swath on each side of its sub-satellite track into twenty-four σ_{o} cells, each having 25km spatial resolu-This 600km swath enables ov cr 95% of the Earth's oceans to be viewed

at least once in every two day period. Several σ_o cells are combined in t h c ground processing to obtain wind v c locity estimates having spatial dimensions of 50km by 50km.

V. Desert:ptlon of the NSCAT Instrument

Four major physical subsystems comprise the NSCAT instrument, The Radio Frequency Subsystem (RFS) contains the transmitter and receiver chains; a Digital Data Subsystem (DSS) provides instrument control, data formatting, digital Doppler processing and telemetry; the antenna subsystem (Ant) consisting of 6 identical, dual-polarization fan beam antennas deployed by four mechanisms; and the system waveguide and harness.

The basic function of the RFS is to gencrate the transmitted pulses at 13.995Ghz and route them to the antenna subsystem through a switch matrix; to receive the returned signal, down convert and pass the signal to the DSS; and to provide a noise source for onboard calibration of the instrument and accurate measurement of transmitter power.

The DSS consists of two processors: a command and control processor w h i ch controls the operations of the instrument, collects housekeeping data and form als downlink telemetry; and a Doppler which digital processor achieves along-beam resolution utilvarying izing the spatially Doppler shift of the returned signal and integrates multiple pulses for each alongbcam cell.

To achieve the desired fan beam i 11 u mination pattern on the Earth's surface, the individual NSCAT antennas are approximately 3.1m long and have a 15cm x 15cm cross-section. Electrically, the feed horns each produce a fan beam with a 25° beamwidth in elevation (along-beam) and a very n a rrow 0.4° beamwidth in azimuth (cross-

beam). Each antenna assembly consists of two end-fed waveguide arrays in a horn (one for v-pol and one for h -pol radiation) supported by a graphite -cpoxy structural member. While each of the antennas has both vertical and horizontal horns, only the vertical polarization is used for antennas 1, 3, 4, and 6 (refer to Fig. 3) while antennas 2 and 5 use both polarizations.

The antenna deployment design cmploys a pyro-activated launch restraint bolt to release the antennas after launch and an aluminum hinge m cchanism using viscous-damped springs for the actual deployment. A more complete description of the in strument can be found in Ref. 5.

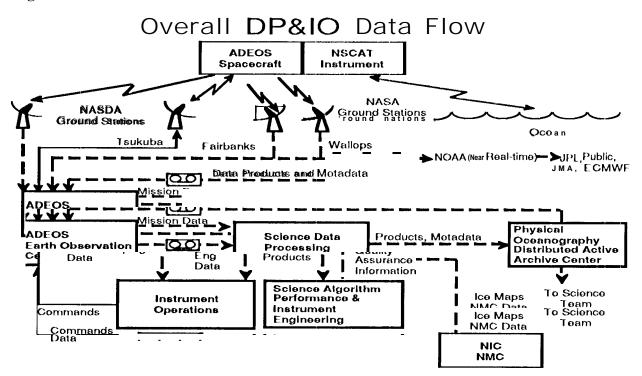
VI. NSCAT Ground System

The NSCAT ground system is shown in Figure 4. The data from the NSCAT in strument is returned via two independent communication paths: one for high-quality science and one for n c a r real time operational uses. The science data stream is collected by the Earth

Receiving Station at NASDA'S Earth Observation Center (EOC) in Hatayama, Tapes with the processed level Japan. zero data (i.e. time ordered, redundant raw data) are sent weekly to the Jct Propulsion Laboratory (JPL) for higher level processing. After proc essing at JPL by the NSCAT Project, a suite of higher level products will b c distributed weekly to users by the Physical Oceanography Distributed Active Archive Center, also located at J]' ... The NSCAT science products will b c distributed approximately three weeks after acquisition of data and will be the most accurate and complete product suite produced by the NSCAT Project.

Separately from the science stream, the operational data streams will b c collected by US ground stations i n Alaska and Virginia and the EOC, and processed by the National Oceanic and Administration Atmospheric within three hours of acquisition. NOAA will distribute the products both domestically and internationally usc by other meteorological agencies.

Figure 4.



The standard data products that will b c generated include: σ_o wind vector cell product - 13arlh-located σ_0 cells in subtrack wind vector cells with qual i t v flags over ocean; vector wind product (or winds in swath) - wind speed and direction in the instrument swath and containing the number of σ_0 's used for wind retrieval, quality flags, the multiple wind vector solutions, and the selected vector; and global wind map product - time averaged, space av er aged wind vectors on a global grid. standard products are described further in Figure 5. Special products will also be generated, including: a high merged geophysical resolution product - Fjar[h-located σ_0 and vector wind measurements collocated in 25km x 25km wind vector cells; and a σ_o beam product - σ_0 organized by beam. Both special products provide coverage ov cr land and ice, as wcll as oceans. Both the standard data products and the special products are available through the Physical Oceanography Distributed Active Archive Center at JPL NASDA's Earth Resources Observation Center.

Figure 5.
NSCAT Standard Data Products

Level 1.7 Data Files

Oceana only, in 24-cell rows o! 50km wind vector cells

- Up to 24 Sigma0s par cell (typically -1 6)

Level 2 Data Files

- Rev-based files organized by wind vector call row (50km cells)
- Each row has 12 cells on each side (600km swaths)
- Each cell contains up to 4 wind combinations of speed and direction (in likelihood order) and selected solution after ambiguity removal.
- Files
- One day average global map gridded at .5 degree resolution from +75 to -75 latitude (720 cells by 300 calls)
- Each cell contains ten averaged parameters (e.gavg wind vectors, avg speed, rmsspeed, wind vectorstd dev, map day fractions)

In addition to the two aforementioned data streams which will be widely disseminated, a near real time data stream (<24 hours since acquisition) is generated by the EOC Processing Center and sent electronically to the NSCAT Project at JPL for processing. This data is used for monitoring instrument health and,

during the early portion of the mission, for performing initial calibration and validation of the data products,

The real time spacecraft and instrument operations are performed by NASDA engineers at the Tracking And Control Center (TACC) in Tsukuba Space Center in Tsukuba, Japan. The NSCAT Project performs engineering trend analysis and command generation a t JPL. Commands are transferred electronically from JPL to EOC, are merged with other instrument and spacecraft commands, and sent to TACC for t ran smission to the spacecraft.

VII. Ear v Results

The NSCAT instrument was launched successfully on August 17, 1996 from Tancgashima Space Center in Tanc gashima, Japan aboard an 11-11 rocket. Although initially 20km too high, NASDA successfully commanded spacecraft to lower its orbit to the operating 797km, sun synchronous orbit. Eleven hours after launch, the NSCAT were successfully deployed. antennas Power was applied to the heater clements of the electronic units to main tain required temperatures until electrical turn-on on September 10, 1996,

After turn-on, the instrument stepped through each of its operating modes, spending several hours in each, All temperatures and modes have b c en nominal to date.

First science data was returned to JPL on September 10, 1996. The data con sisted of a single revolution with primary ocean coverage over the North The data was processed suc-Atlantic. cessfully by ground computers w i thin two hours. Typical results include wind vectors in swath (Figure 6) and global averaged wind vectors (Figure 7). During the five-day checkout perriod, the instrument performed both calibration measurements and experimental high resolution wind measurements of 6km x 6km. Upon conclusion

of the checkout activities, the instrument was commanded into the wind observation mode, in which it will remain until the end of mission. Also during the checkout period, the communication paths to the ground stations were verified, as was the ability to process the science and operational data streams.

Figure 6. Wind Vectors in Swath

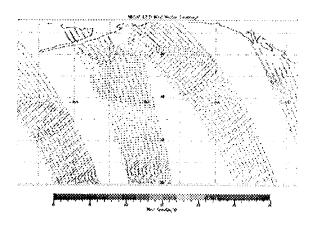
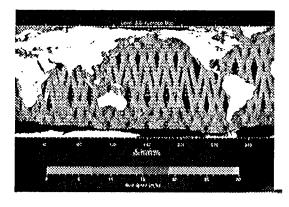


Figure 7. Global Average Winds



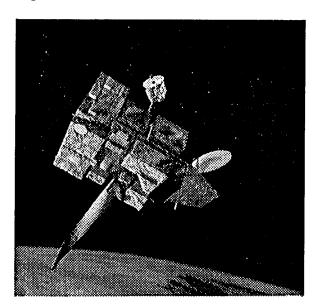
VIII. Description of the SeaWinds nstrument

The ScaWinds scatterometer represents a different approach to the spaceborne scatterometer design. ScaWinds will Usc a conically scanning "pencil-beam" antenna to map the sca surface. The scanning sing]c-aperture antenna is used to form two narrow beams, yielding an instrument that physically is significantly more compact than the c fan-beam design. The ScaWinds an -

tenna will rotate conically with respect to the nadir-looking axis of the space-craft. The scanning design imposes less stringent FOV constraints than the cfan beam design; allows for a reduction in spacecraft power requirements; reduces the overall mass of the instrument; and eliminates the need for deployment mechanisms, although a release v-band is required. Conversely, the design requires the antenna to be crotated at 18 rpm, and the σ_o resolution size is dependent on the real aperture of the antenna, i.e. antenna dimensions.

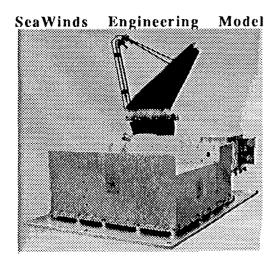
The planned orbit for the ADFOS II satellite is, again, a sun synchronous (99°) inclination angle but at 803km The resulting orbit repeat pc altitude. riod is 4 days versus the ADEOS spacecraft's 41 days. The ADEOS II Mission and the ScaWinds Experiment have a design life of 3 years, with a five-year goal. A Ku-band carrier frequency of 13.402GHz was selected f o r ScaWinds to satisfy both the scatterometer objectives and recent changes in spectrum allocations. A conceptual diagram of the ScaWinds onboard t h c ADEOS II satellite is shown in Figure 8.

Figure 8. SeaWinds on ADEOS 11



The three major subsystems of the i n arc the conical-scan Winds antenna subsystem (SAS), th c ScaWinds electronics subsystem (SES), and the command and data subsystem (CDS). Figure 9 shows a photograph of the ScaWinds engineering model units now in integration and testing. CDS provides the command and data i n terface to the spacecraft, controls t h c instrument configuration and operation mode, provides real-tirne generation of the Doppler 2nd-range tracking parameters for the SES and processes and formats the science and engineering telemetry for downlinking. The SES contains the transmitter chain, including a coupled-cavity 110W travcling wave tube, and the receiver chain, and also digitizes the RFsignal before transmitting it to the CDS.

Figure 9.

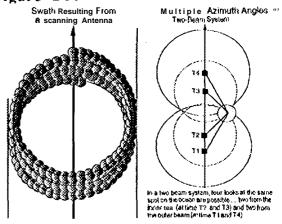


The SAS contains an antenna dish of about 1.1m in diameter; two separate feeds producing two slightly elliptical microwave beams; electronic controls; and the spin actuator. A rotary wave - guide coupler is used to transfer rad i a - tion energy between the rotating a n - tenna aperture assembly and the stationary radio-frequency electronics. The elevation or look angles of the two antenna beams are 40° and 46° with respect to nadir. At the planned orbit height of 803 km, the incidence angles

of the beams are about 46° and 54° respectively. The beams are electrically polarized "in the heizontal (perpendicular to the incidence plant) for the inner, or 40°, beam, and in the vertical for the outer, or 46°, beam. Reference 6 describes in greater detail the ScaWinds design.

The antenna beamwidth will produce a footprint on thc antenna Earth's surface of approximately 25km This footprint pattern deby 35km. fines the basic surface resolution cell dimension for measuring the radar backscattering coefficient, σ_0 . The σ_0 's arc combined on the ground, as in th c NSCAT processing, to achieve 50km x 50km wind vector cells. The radius o f the helical circles formed on the surface by the two scanning beams a re 700km and 900km, respectively. Figure 10 depicts the ground geometry created by the ScaWinds antenna FOV.

Figure 10.



The ScaWinds scatterometer will cov cr more than 90% of the Earth's surface in only onc day. However, the Sc a-Winds viewing geometry results in three distinct regions in the instrument swath of differing wind vector quality based on present ambiguity removal techniques. The middle region of the swath satisfies the science require.ments and is comparable in size to the NSCAT coverage. The two-beam arrangement allows each spot in the

primary radar mapping swath to b c viewed from up to four azimuth look directions.

With looks separated by approximately 180°, the innermost region has relatively poor azimuthal diversity consequently, requires new ambiguity removal techniques to satisfy the directional accuracy. The outermost r c gion has coverage from only one beam, has little angular separation between measurements, and also has poor azimuthal diversity. Consequently, it also requires ncw ambiguity removal schemes. Studies by the ScaWinds scicncc team members arc presently u n derway and show promise in removing the directional ambiguities and m ay make data from the entire ScaWinds swath satisfy the science requirements.

IX. Cummary

The NSCAT instrument is presently in orbit and returning high quality data. The ScaWinds instrument is under full-scale development and is planned for launch so as togenerate a continuous time-series of scatterometer extending over six or more years. The scatterometer products are actively being used by the research, operational, and commercial communities.

Acknowledgment

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